

Laws of Object-Orientation with Reference Semantics

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Abstract. Algebraic laws have been proposed to support program transformation in several paradigms. In general, and for object-orientation in particular, these laws tend to ignore possible aliasing resulting from reference semantics. This paper proposes a set of algebraic laws for object-oriented languages in the context of a reference semantics. Soundness of the laws is addressed, and a case study is also developed to show the application of the proposed laws for code refactoring.

1 Introduction

Object-oriented programming is largely used for potentially increasing the productivity of software development and there is a great interest on formalisms that allow reasoning about object-oriented programs.

Several approaches to formalise the semantics of object-oriented languages have been proposed. For example, Abadi and Leino [1] introduce a logic similar to Hoare Logic [2] for reasoning about object-oriented programming and prove its soundness. Müller and Poetzsch-Heffer [3] introduce some general techniques for object-oriented program verification. Cavalcanti and Naumann [4] propose an object-oriented language, ROOL, which is a subset of sequential Java combined with some refinement constructs such as specification statements as in [5]. The semantics of ROOL is based on weakest preconditions and adopts the copy mechanism. He et al [6] propose rCOS, a reference semantics for an object-oriented language, based on the Unifying Theories of Programming (UTP) [7],

* We thank Márcio Cornélio for profitable discussions about this work. The authors thank CNPq, the Brazilian research agency, for financial support. Leila Silva thanks UNU-IIST for financial support for her visit to this institute.

which considers the reference mechanism. The logic of rCOS is a conservative extension of standard predicate logic [7]. Santos et al [8] also define a semantics for an object-oriented language, based on the UTP; this work addresses a copy semantics and considers pointers as a separate and complementary theory [9].

Many paradigms have benefited from algebraic programming laws, among them imperative programming [10], functional programming [11], logic programming [12] and concurrency [13]. These laws state properties that relate programming constructs. Nevertheless, programming laws for the object-oriented paradigm are not yet well established. Laws for small grain object-oriented constructs have been considered in [14, 15]. The work of Borba et al [16] is a significant contribution in this direction. They propose laws of commands and of classes for ROOL, therefore restricted to copy semantics. Cornélio [17] proves all the laws proposed in [16] and shows how these laws can be used to formalize some of the refactorings informally proposed by Fowler [18]. He et al [6] also propose a set of laws for an object-oriented language, in the context of rCOS. These laws are very similar to the ones presented in [16] and the proofs in the context of a reference semantics are omitted. Furthermore, laws valid exclusively in the context of reference semantics have not been investigated.

In this paper we present laws for object-oriented languages considering a reference semantics. We consider laws that are valid both for copy and reference semantics, revise some laws that are valid for copy but not for reference semantics, and propose new laws that hold only for reference semantics. As far as we are aware, this is an entirely new contribution. In particular, we use the rCOS semantics to prove soundness of each proposed law, as illustrated in this paper and more detailed in [19]. We also develop a simple case study to show the applicability of the proposed laws for improving code structure.

This paper is organized as follows. Section 2 summarises the rCOS semantics. Section 3 briefly discusses copy versus reference semantics and introduces some laws valid exclusively in the context of reference semantics. Applications of the proposed laws related to code refactoring are the subject of Sect. 4. Section 5 presents some final considerations and directions for future work. Finally, in Appendix A we illustrate the style for proving the proposed laws.

2 The rCOS Approach

To prove the soundness of the laws introduced in this paper, we need to use a semantics for object-oriented languages that considers references. We adopt rCOS [6], which is based on the Unifying Theories of Programming (UTP) [7]. This section summarizes some relevant aspects of rCOS.

2.1 Syntax of rCOS

In rCOS an object system (or program) S is of the form **Cdecls** • **Main**, where **Cdecls** consists of a class declaration section and **Main** a main method. The main method is a pair (**externalvar**, **c**), where **externalvar** is a finite set of

global variables and c is a command (the program control flow). The declaration section is a finite set of class declarations $cdecl_1; cdecl_2; \dots; cdecl_k$, where each class declaration $cdecl_i$ has the form given in what follows.

```
[private] class M [extends N] {
    [private  T11 a11 = d11, ..., T1r a1r = d1r;]
    [protected T21 a21 = d21, ..., T2s a2s = d2s;]
    [public    T31 a31 = d31, ..., T3t a3t = d3t;]
    [method m1(V11 x1; V12 y1; V13 z1){c1};...
        mℓ(Vℓ1 xℓ; Vℓ2 yℓ; Vℓ3 zℓ){cℓ};]}

```

The square brackets mean that the enclosed term is optional. A class can be declared **private** or **public**, but only public classes or a primitive type can be used as global variable types in **Main**. Attributes can be **private**, **protected** or **public** and a method declaration declares its value parameters ($V_{i1} x_i$), result parameters ($V_{i2} y_i$), value-result parameters ($V_{i3} z_i$) and body (c_i). All methods are public. rCOS supports the following commands:

$$c ::= \text{SKIP} \mid \text{CHAOS} \mid \text{var } T \ x \ [=e] \mid \text{end } x \mid c_1; c_2 \mid c_1 \triangleleft b \triangleright c_2 \mid \\ c_1 \sqcap c_2 \mid b * c \mid \text{le.m}(e_1; e_2; e_3) \mid \text{le} := e \mid C.\text{new}(\text{le})$$

The command **SKIP** does nothing and terminates successfully, whereas **CHAOS** is the most nondeterministic process. Variables can be declared with **var** and undeclared with **end**. Variables may include an optional initialization. Sequential composition ($;$), conditional choice ($\triangleleft \triangleright$), non determinism (\sqcap) and iteration ($*$) are provided. The arguments of a method call le.m obey value, result and value-result parameter passing mechanisms, respectively. The term le stands for an expression that can appear on the left-hand side of an assignment. Such expressions are called *left-expressions* and obey the form $\text{le} ::= x \mid \text{self} \mid \text{le.a} \mid (C) \text{le}$, where x is a variable and a an attribute. An expression e is of the form $e ::= x \mid a \mid \text{null} \mid \text{self} \mid e.a \mid (C)e \mid f(e)$, where **null** is a null reference, **self** is used to denote the active object, $e.a$ is the attribute a of e , $(C)e$ is type casting and f is a built-in operation for a primitive type. The term e_1 is a list of expressions, whereas e_2 and e_3 are lists of left-expressions.

2.2 Semantics of rCOS

In rCOS, the semantics of a program is the combination of its static and dynamic semantics. The static semantics comprises a class declaration and a declaration section. The dynamic semantics addresses a command and the entire program. For conciseness, we detail only the dynamic semantics of some constructs, enough for understanding the proof show in Appendix A; see [6] for further details.

The static semantics is captured by the *structural variables*, denoted by Ω , which do not change during the execution of the program. These variables record, for example, the set of names, denoted as *cname*, of the private and public classes, the set of private, protected and public attributes of a given class, the

direct superclass of a class and a mapping $op(C)$ that associates to each class C the list of methods of C .

The dynamic semantics use dynamic variables, which comprise program variables, a variable *visibleattr* (that records the visible attributes) and a variable π that represents the system configuration.

Program variables include global (denoted *externalvar*) variables, which are the variables declared in the main method, and local variables (denoted *localvar*), declared by local variable declaration commands. Local variables include *self* (whose value represents the current active object) and parameters of methods. The union of global and local variables is denoted by *Var*.

As method calls may be nested, *self* and parameters may be declared a number of times with possible different types before they are undeclared. Thus, a local variable x is represented by a sequence of declared types

$$x : TypeSeq, TypeSeq ::= \langle T_1, T_2, \dots, T_n \rangle.$$

The declared type of x is retrieved by the function $dtype(x)$. The term \bar{x} is used to denote the value of a local variable x , which is in fact a sequence of values, the head representing the current value of x , denoted by $value(x)$.

A value is either a member of a primitive type or is an object identity in *REF* with its dynamic typing information. *REF* is a set of object identities (or references) and includes *null*. For a value $v = \langle r, C \rangle$, $ref(v)$ denotes the reference r of v and $type(v)$ the current type C of v .

An object o is either the special object *null* or a structure $\langle r, C, \sigma \rangle$, where σ is the state of o , denoted $state(o)$, mapping each attribute a visible in C into a value of the declared type of a .

The visibility of attributes is captured by a dynamic variable *visibleattr* that records the set of attributes visible to the command under execution. The value of *visibleattr* defines the current execution environment.

The value of the system configuration π is the set of objects created so far. When a new object is created or the value of an attribute of an existing object is modified, the system configuration changes. We use $\pi(C)$ to denote the set of existing objects of class C .

In the UTP a program is represented by a design $D = (\alpha, P)$ where α denotes the set of variables of the program and P is a predicate of the form

$$p(x) \vdash R(x, x') \stackrel{def}{=} (ok \wedge p(x)) \Rightarrow (ok' \wedge R(x, x'))$$

where $x, x' \subseteq \alpha$ stand for the initial and final values of a variable; p is the precondition, defining the initial states; R is the postcondition, relating the initial and final states; ok, ok' describe initiation and termination of the program and do not appear in expressions or assignments of the program texts. Designs can be framed and the domain of designs is closed under sequential composition, choice and iteration. Refinement relation between design is defined as logic implication.

As rCOS is based on the UTP, the semantics of a command is defined using the dynamic variables. Each command c has its well-defined conditions $\mathcal{D}(c)$, as part of the precondition of the semantics of c ; the semantics of c , denoted $\llbracket c \rrbracket$,

has the form of $\mathcal{D}(c) \Rightarrow (p \vdash R)$. In what follows we give the semantics of local declaration and undeclaration, assignments and method call. The semantics of other constructors can be found in [6].

Local variable declaration and undeclaration. Local variables are represented as sequences of declared types and values. When a variable is declared the corresponding sequences are modified to add a new elements in their heads. The command $\text{var } T \ x = e$ declares a variable and initializes it. The semantics is given below, where the symbol \preceq stands for a subclass relation.

$$\begin{aligned} \mathcal{D}(\text{var } T \ x = e) &\stackrel{\text{def}}{=} (x \in \text{localvar}) \wedge \mathcal{D}(e) \wedge \\ &\quad \text{type}(e) \in \text{cname} \Rightarrow \text{type}(e) \preceq T \\ \llbracket \text{var } T \ x = e \rrbracket &\stackrel{\text{def}}{=} \{x\} : \mathcal{D}(\text{var } T = e) \vdash (\bar{x}' = \langle \text{value}(e) \rangle . \bar{x}) \wedge \\ &\quad \text{TypeSeq}'(x) = \langle T \rangle . \text{TypeSeq}(x). \end{aligned}$$

The command $\text{end } x$ terminates the current scope of variable x . Thus, the heads of the sequences of x are removed.

$$\begin{aligned} \mathcal{D}(\text{end } x) &\stackrel{\text{def}}{=} (x \in \text{localvar}) \\ \llbracket \text{end } x \rrbracket &\stackrel{\text{def}}{=} \{x\} : \mathcal{D}(\text{end } x) \vdash (\bar{x}' = \text{tail}(\bar{x})) \wedge \\ &\quad \text{TypeSeq}'(x) = \text{tail}(\text{TypeSeq}(x)). \end{aligned}$$

Assignments. An assignment has two forms, depending on whether le is a variable x or has the form $le.a$. In the first case, the current value of the variable is changed. In the second case, the value of an attribute a of object le is modified.

$$\begin{aligned} \mathcal{D}(le := e) &\stackrel{\text{def}}{=} \mathcal{D}(le) \wedge \mathcal{D}(e) \wedge \text{type}(e) \in \text{cname} \Rightarrow \text{type}(e) \preceq \text{dtype}(le) \\ \llbracket x := e \rrbracket &\stackrel{\text{def}}{=} \{x\} : \mathcal{D}(x := e) \vdash (\bar{x}' = \langle \text{value}(e) \rangle . \text{tail}(\bar{x})) \\ \llbracket le.a := e \rrbracket &\stackrel{\text{def}}{=} \{\pi(\text{dtype}(le))\} : \mathcal{D}(le.a := e) \vdash \\ &\quad (\pi(\text{dtype}(le))' = \pi(\text{dtype}(le)) \uplus \\ &\quad \{o \oplus \{a \mapsto \text{value}(e)\} | o \in \pi \wedge \text{ref}(o) = \text{ref}(le)\}). \end{aligned}$$

The overriding (\oplus) of an object $o = \langle r, M, \sigma \rangle$ to record the new value d of attribute a is defined as $o \oplus \{a \mapsto d\} = \langle r, M, \sigma \oplus \{a \mapsto d\} \rangle$. For a set $S \subseteq O$ of objects, $S \uplus \{\langle r, m, \sigma \rangle\} \stackrel{\text{def}}{=} (S \setminus \{o | \text{ref}(o) = r\}) \cup \{\langle r, M, \sigma \rangle\}$.

Notice that this definition requires dynamic type matching and the type of the object needs to be consistent with the declared type. When le is x , the new value of x is now the head of the sequence of values, replacing the old value of x in the current scope. In the other case, the attached object is found in the system configuration π and its state is modified accordingly.

Method Call. For a method signature $m(V_1 \ x; V_2 \ y; V_3 \ z)$ let ve, res and vre be list of expressions representing the arguments passed by value, result and

value-result mechanisms. The semantics of $le.m(ve; re; vre)$ is as follows.

$$\begin{aligned}
\mathcal{D}(le.m(ve; re; vre)) &\stackrel{def}{=} \mathcal{D}(le) \wedge \text{type}(le) \in \text{cname} \wedge (le \neq \text{null}) \wedge \\
&\quad \exists N \in \text{cname}. (\text{type}(le) \preceq N) \wedge \\
&\quad \exists (m \mapsto (V_1 \ x; V_2 \ y; V_3 \ z, c_1) \in \text{op}(N)) \\
\llbracket le.m(ve; re; vre) \rrbracket &\stackrel{def}{=} (\mathcal{D}(le.m(ve; re; vre)) \Rightarrow \exists C \in \text{cname}. (\text{type}(le) = C) \wedge (\\
&\quad \llbracket \text{var } V_1 \ x = ve; V_2 \ y; V_3 \ z = vre \rrbracket; \\
&\quad \llbracket \text{var } C \ \text{self} = le \rrbracket; \llbracket \text{Execute}(C.m) \rrbracket; \llbracket re, vre := y, z \rrbracket; \\
&\quad \llbracket \text{end self}, x, y, z \rrbracket).
\end{aligned}$$

If method m is not declared in C but in a superclass N of C then

$$\llbracket \text{Execute}(C.m) \rrbracket \stackrel{def}{=} \llbracket \text{Execute}(M.m) \rrbracket,$$

where M is the immediate superclass of C and $M \preceq N$. Given a class A and a method m the semantics of $\text{Execute}(A.m)$ comprises setting the execution environment, then executing the body of the method and finally resetting the environment. Thus, $\llbracket \text{Execute}(A.m) \rrbracket \stackrel{def}{=} \text{Set}(A); \text{body}(A.m); \text{Reset}$, where $\text{Set}(A)$ sets the variable *visibleattr* with the set of attributes visible in class A , that is, attributes of A , public and protected attributes inherited from superclasses of A , and public attributes of public classes. Reset sets the variable *visibleattr* to the set of attributes that are accessible by the main program, that is, the public attributes of public classes. The term $\text{body}(A, m)$ is the body c of method m . The prefix *self* is added to each attribute and method in c , to guarantee that the environment is set correctly when a nested method call that may change the execution environment is completed. See [6] for a detailed explanation.

Based on the semantics of a class declaration, $\llbracket Cdecls \rrbracket$, and on the semantics of commands, $\llbracket c \rrbracket$, the semantics of a program is defined as

$$\begin{aligned}
\llbracket Cdecls \bullet \text{Main} \rrbracket &\stackrel{def}{=} \exists \Omega, \Omega', \text{internalvar}, \text{internalvar}' \bullet (\llbracket Cdecls \rrbracket; \text{Init}; \llbracket \text{Main} \rrbracket), \\
\text{Init} &\stackrel{def}{=} \mathcal{D}(Cdecls) \vdash \text{visibleatr}' = \emptyset \wedge \pi' = \emptyset \quad \wedge \quad \bigwedge_{x \in \text{Var}} (\bar{x}' = \langle \rangle \wedge \text{Typeseq} = \langle \rangle), \\
\llbracket \text{Main} \rrbracket &\stackrel{def}{=} \mathcal{D}(\text{Main}) \Rightarrow \llbracket c \rrbracket,
\end{aligned}$$

where *internalvar* is the set of variables in *localvar*, π and *visibleattr*, *Init* corresponds to the initialization of variables, and *Main* is the main program.

3 Laws

The main difference between copy and reference semantics is the possibility of aliasing when the reference semantics is considered. Aliasing can occur through

assignments and parameter passing. Aliasing can cause a range of difficult problems within object-oriented programs, because a referring object can change the state of the aliased object, implicitly affecting all the other referring objects [20].

A comprehensive set of laws of an object-oriented language based on copy semantics has been proposed in [16]. This work distinguishes command laws and laws for classes. As aliasing is related to assignment and parameter passing, the laws for classes proposed in [16] are also valid for reference semantics. These laws deal, among other constructs, with changing visibility of attributes (from private to protected and from protected to public), introducing new class declarations, removing unused classes, introducing fresh attributes, removing unused attributes, introducing new methods, removing redundant or unused methods, introducing inheritance, and moving attributes and methods to a superclass.

Nevertheless, some command laws are not valid in the context of reference semantics, and here we propose adaptations of such laws for this new context (Sect. 3.1). Moreover, we propose new laws valid only in the context of a reference semantics (Sect. 3.2). We briefly address soundness by presenting the proof of one of these laws in Appendix A, using the rCOS semantics, given in Sect. 2.

An important point to notice is that we consider reference semantics assuming that expressions are side-effect free, as in Java [21], which does not allow pointer manipulation, and attaches a copy semantics to assignments involving variables of primitive types.

Before presenting new laws, we reproduce here laws 1 (var elim), 2 (var final value) and 3 (;- \triangleleft distrib), valid for both copy and reference semantics, as they are used in the development of the case study of Sect. 4.

We say that a variable of process c_1 is *free*, denoted $\text{free}(c_1)$, if it is not declared in the local block under consideration, and *bound* otherwise. Similarly, we use $\text{free}(e)$ for the free variable of an expression e . If a declared variable is never used, its declaration has no effect.

Law 1 (var elim) $\text{var } T \ x; \ c; \text{ end } x = c, \text{ if } x \notin \text{free}(c).$

There is no point in assigning to a variable at the very end of its scope. Moreover, evaluation of a condition is not affected by what happens afterwards, and therefore sequential composition distributes leftwards through a conditional. These facts are captured by the next two laws, respectively.

Law 2 (var final value) $\text{var } T \ x; \ c; \ x := e; \text{ end } x = \text{var } T \ x; \ c; \text{ end } x$

Law 3 (;- \triangleleft distrib) $(c_1 \triangleleft b \triangleright c_2); \ c_3 = (c_1; \ c_3) \triangleleft b \triangleright (c_2; \ c_3)$

3.1 Revising Laws Valid only for Copy Semantics

There are laws valid for copy semantics that, in general, are not valid for reference semantics. In what follows we discuss the problems that arise in some of these laws and we introduce a revised law valid for reference semantics. A more complete set of such laws can be found in [19].

The sequential composition of two assignments to the same list of variables is easily combined to a single assignment, when copy semantics is considered.

Law 4 (combine assignments) $le := e; le := f = le := f[e/le]$

The notation $f[e/le]$ denotes the substitution of le by the free occurrences of e in f . In the context of reference semantics, this law does not hold in general when le is a reference to an object. Assuming that le is a reference, we consider two kinds of assignments, depending on the form of le . If le is a variable x , the law is still valid, as it corresponds to two consecutive associations of objects to le , which is equivalent to the last association. However, if le is of form $le.a$, the following situation might happen. Assume x and y reference the same object, say an account with balance 2; the sequence of assignments

$x.balance := y.balance + 1; x.balance := y.balance + x.balance$

increases the balance attribute to 6, whereas the combined assignment

$x.balance := y.balance + (y.balance + 1)$

updates it to 5.

To be valid for reference semantics we must introduce conditions on the application of the law. In this case, if there is no aliasing between variables of le and variables of f , the law is sound. We introduce the function $nosh(le, f)$ to capture this fact, where $nosh$ stands for ‘no sharing’; it yields true in the absence of aliasing. Thus, for reference semantics the law is as follows.

Law 5 (revised combine assignments)

If $nosh(le, f)$ then $le := e; le := f = le := f[e/le]$.

The computation of $nosh$ depends on the context of the transformation. A precise definition of $nosh$ clearly requires dynamic analysis. For the purposes of program transformation, however, it is desirable that the side conditions be syntactic. Through a static analysis of the relevant program context we are able to decide if there is a possibility of aliasing. To perform this analysis a graph that captures the dependency among variables is constructed and examined (see [19]), based on some ideas of [22, 23].

If two consecutive assignments do not share data, the order does not matter. For copy semantics the following law is valid.

Law 6 (order independent assignments)

$le_1 := e; le_2 := f = le_2 := f; le_1 := e$,
provided $le_1 \notin free(f)$ and $le_2 \notin free(e)$.

This law presents a similar problem as the one discussed in Law 4 (combine assignments). If le_1 and le_2 have the form x , this corresponds to the attachment of a new value to these variables and the effect is the same as for variables of primitive types. However, if either le_1 or le_2 is of the form $le.a$ the conditions $nosh(le_1, f)$ and $nosh(le_2, e)$ are required. The modified law for reference semantics is as follows.

Law 7 (revised order independent assignments)

If $(nosh(le_1, f) \wedge nosh(le_2, e) \wedge le_1 \notin free(f) \wedge le_2 \notin free(e))$ then
 $le_1 := e; le_2 := f = le_2 := f; le_1 := e$.

Assignment distribution rightwards through a conditional; the next law is also valid only for copy semantics.

Law 8 (assignment- \triangleleft distrib) If $le \notin \text{free}(b)$ then
 $(le := e); c_1 \triangleleft b \triangleright c_2 = (le := e; c_1) \triangleleft b \triangleright (le := e; c_2)$

If le is of the form x , this corresponds to an association of a new value to le and as le does not occur in b , the assignment can safely take place after b evaluation. However, if le is of the form $le.a$ the condition $\text{nosh}(le, b)$ is required. The modified law for reference semantics is presented below.

Law 9 (revised assignment- \triangleleft distrib 1) If $(\text{nosh}(le, b) \wedge le \notin \text{free}(b))$ then
 $(le := e); c_1 \triangleleft b \triangleright c_2 = (le := e; c_1) \triangleleft b \triangleright (le := e; c_2)$.

However, a particular case of this law is valid for both copy and reference semantics. Consider an assignment $le := e$. Assuming that le is an object identifier, this creates an aliasing between le and e . Such an assignment distributes leftwards through a conditional, if the condition contains occurrences of e , but no further aliasing with le .

Law 10 (revised assignment- \triangleleft distrib 2) If $\text{nosh}(le, b[\text{null}])$ then
 $(le := e); c_1 \triangleleft b[e] \triangleright c_2 = (le := e; c_1) \triangleleft b[e] \triangleright (le := e; c_2)$.

The notation $b[e]$ means that b might contain occurrences of e . The condition $\text{nosh}(le, b[\text{null}])$ captures that there is no sharing between le and b ; null is used in place of e ($b[\text{null}]$) to check that le has no further aliasing with b .

3.2 Laws Valid only for Reference Semantics

The introduction of aliasing motivates the investigation of new laws. In this section we introduce laws valid only in a context of reference semantics. We are also considering as an implicit condition that le refers to an object, so it is not a variable of a primitive type. We use the notation le_o to remark this fact.

Permutation of assignments are possible in some situations.

Law 11 (assignment permutation)
 $c; le_o := e = le_o := e; c$, provided $\forall x \notin \text{free}(c) \bullet \text{nosh}(le_o, x)$.

This law is not valid in general for copy semantics as the value of e might be altered in c and, in this case, le_o will hold the old value on the right-hand side of the law. This problem does not arise in reference semantics because le_o and e are aliased and any change in e on the right-hand side will also reflect in le_o .

If two variables are aliased, it does not matter which one is chosen to use.

Law 12 (assignment seq substitution) $le_o := e; c = le_o := e; c[e/le_o]$, provided the aliasing of le_o and e is preserved in c .

To check the aliasing of le_o and e it is enough to do an inspection of the code and check the condition $\neg(\text{nosh}(le_o, e))$.

To see why this law is not valid for copy semantics, consider the case in which e is z and c is a method call $z.m()$, where m is a method that updates an attribute of the object referenced by z . By applying the law we have

$$le_o := z; z.m() = le_o := z; le_o.m().$$

If we consider reference semantics, this equality is valid as z and le_o refer to the same object. However, in the context of copy semantics this is not the case; on the left-hand side the object referenced by z is updated, whereas on the right-hand side the object referenced by le_o is modified and they are distinct objects.

As mentioned before, alias can occur through assignments and parameter passing. Thus, there are analogous laws to the previous one that substitute the assignment by a method call to m through which the aliasing between le_o and e occurs. There are several situations to consider. For example, the method call could be $le_o.m(\emptyset, \emptyset, e)$ and the body of m includes an assignment $\text{self} := e$. In another context, both le_o and e could be passed as result or value-result arguments of m and the body of m includes an assignment $x := y$, where x and y are the formal parameters that match le_o and e , respectively. The aliasing between le_o and e may occur in a sequence of nested method calls, and so on.

To abstract all situations in which aliasing could happen, we introduce the notation $c[\text{alias}(le_o, e)]$, meaning that c is a command that establishes an alias between le_o and e . The previous law can be generalized as follows.

Law 13 (aliasing seq substitution)

$c_1[\text{alias}(le_o, e)]; c_2 = c_1[\text{alias}(le_o, e)]; c_2[le_o/e]$,
provided the alias of le_o and e is preserved in c_1 .

If two variables le_{o1} and le_{o2} are aliased, sequential assignments of le_{o1} to le_{o2} and vice-versa have no effect.

Law 14 (consecutive sequential assignment)

$c[\text{alias}(le_{o1}, le_{o2})] = c[\text{alias}(le_{o1}, le_{o2})]; le_{o1} := le_{o2}$
 $= c[\text{alias}(le_{o1}, le_{o2})]; le_{o2} := le_{o1}$

As le_{o1} and le_{o2} reference the same object, the last assignment after executing c can be regarded as the skip command in the previous law and, therefore, can be removed. However, for copy semantics, the final assignment cannot be eliminated, otherwise the updating of le_{o1} (or le_{o2}) is not perceived by le_{o2} (or le_{o1}).

4 Application: Code Refactoring

The proposed laws can be used to formalize refactorings and, more generally, to improve code structure. For example, Rule 1 (extract/inline method) expresses the Extract/Inline refactoring [18], which can be proved using some of the laws presented in Sect. 3 (see [19]). The extract method is used to group code fragments as a new method. The inline method does the opposite task.

Cornélio [17] gives a formalization of this law for copy semantics. In his formalization, types of variables in a must be of a basic type, otherwise changes of objects in m_2 may not be reflected in variables of m_1 . This is a severe restriction in the application of the general refactoring proposed by Fowler. In the context of reference semantics, we are able to deal with the general case.

Let cds be the set of declared classes of program P . Let c be the main command of P . Let A and C be classes of cds .

Rule 1 (extract/inline method)

```
class A extends C{ads;m1(pds1){c1[c2[a]]};mts}
=
class A extends C{ads;m1(pds1){c1'};m2(pds2){c2[α(pds2);mts']}
```

where

$c_1[c_2[a]]$ denotes that $c_2[a]$ is a fragment of code of c_1 ,
 $c_1' \stackrel{def}{=} c_1[\text{self.m}_2(a)/c_2(a)]$, $mts \stackrel{def}{=} mts'[c_2[a]/\text{self.m}_2(a)]$,
 a is the set of variables of c_2 , not including attributes of class A ;

provided

- (1) parameters in pds_2 must have the same types as variables in a ;
- (2) method m_2 is not declared in mts nor in any superclass or subclass of A in cds ;
- (3) m_2 does not appear in c nor in mts , for any $B \preceq A$.

In this rule, from left to right, the fragment of code represented by c_2 is extracted from all methods in A (m_1 and mts) and a new method with body c_2 is created. The modified methods then call the created method. The reverse action is done when applying the rule from right to left.

To apply this transformation we consider some issues, captured by the side conditions associated to the rule. The first condition is obviously necessary to guarantee a safe type matching, and is required in both directions of the rule application. The second condition is necessary for the application from left to right, requiring that the name m_2 be fresh. The third condition is necessary for the application from right to left, to guarantee that only methods of class A calls m_2 and thus it is possible to inline its body.

Similar refactorings can be formalized in an analogous way. To illustrate an application of code restructure that uses the above refactoring and some of the proposed laws, consider a fragment of program that searches and updates an element of an array; this is intentionally unstructured, combining the actions related to search and update into a single method as shown in Fig. 1.

The goal is to transform this program into the one in Fig. 2, in which a method search has been introduced to separate the tasks of updating and searching in different methods.

To improve the code structure we begin with the example of Fig. 1 and by applying some of the laws introduced in Sect. 3, we reach the code depicted in Fig. 2. As each law is proved considering the rCOS semantics (see [19] for

```

class BasicEntity {
  private T1 at1; T2 at2;
  method update(T2 m ;  $\emptyset$ ;  $\emptyset$ ) {at2 := m};
  getat1( $\emptyset$ ; T1 n;  $\emptyset$ ) {n:=at1}}
class Application {
  private BasicEntity data[]; -- assume the last element is null
  method updateApplication(T1 num, T2 value; T2 reply ;  $\emptyset$ )
  {
    Int i = 1;
    Int len, number; Bool stop;
    len := data.length(); stop := false;
    SKIP  $\triangleleft$  data[i] == null  $\triangleright$  {
      (( $\neg$  stop) and (i<=len)) *
      {data[i].getat1( $\emptyset$ , number,  $\emptyset$ );
       stop := true  $\triangleleft$  number = num  $\triangleright$  i := i + 1}}
    {reply := "Failed Updating"  $\triangleleft$  data[i] == null  $\triangleright$ 
     {data[i].update(value,  $\emptyset$ ,  $\emptyset$ ); reply:= "Successful Updating"}}}
  }

```

Fig. 1. Searching and updating an element of an array in a single method.

```

class BasicEntity {... }
class Application {
  private BasicEntity data[]; -- assume the last element is null
  method search(T1 num; BasicEntity obj;  $\emptyset$ ) {
    Int i = 1;
    Int len, number; Bool Stop
    len := data.length(); stop := false;
    SKIP  $\triangleleft$  data[i] == null  $\triangleright$  {
      (( $\neg$  stop) and (i<=len)) *
      {data[i].getat1( $\emptyset$ , number,  $\emptyset$ );
       stop := true  $\triangleleft$  number = num  $\triangleright$  i := i + 1}}
    obj:=data[i]}
  method updateApplication(T1 num, T2 value; T2 reply ;  $\emptyset$ ) {
    BasicEntity elem;
    self.search(num, elem,  $\emptyset$ );
    {reply := "Failed Updating"  $\triangleleft$  elem == null  $\triangleright$ 
     {elem.update(value,  $\emptyset$ ,  $\emptyset$ ); reply:= "Successful Updating" }}}
  }

```

Fig. 2. An example of searching and updating an element of an array.

details), the code transformation is sound. Thus, initially we apply Law 1 (var elim) to introduce a declaration of `obj` in method `updateApplication`. After that, we apply Law 2 (var final value) to introduce the alias between `obj` and `data[i]` (see Fig. 3).

Then we apply Law 3 ($;- \triangleleft \triangleright$ distrib) to move the assignment to `obj` to inside the conditional. Now, we apply Law 7 (revised order independent assignment) twice to permute the assignment to `obj`. In this case, as `data[i]` and `reply` are of different types, `nosh(reply, data[i])` is trivially true, as well as `nosh(obj, k)`,

```

class BasicEntity {...} class Application {...
  method updateApplication(T1 num, T2 value; T2 reply ; ∅)
  { ... BasicEntity obj; ...
    {reply := "Failed Updating"} < data[i] == null >
    {data[i].update(value); reply:= "Successful Updating"}}}
    obj:= data[i];

```

Fig. 3. Applying laws 1 (var elim) and 2 (var final value) in the case study of Fig. 1.

where k is the string data. Moreover, `obj` and `reply` are not on the right-hand side expressions of both assignments. Next, we use Law 11 (assignment permutation) to permute the assignment to `obj`. Then, we use Law 10 (revised assignment- \Leftarrow 2) to permute again the assignment to `obj`. Fig. 4 shows the resulting code. Next, we apply Law 12 (assignment seq substitution) to replace `data[i]` with `obj`. Finally, we apply Rule 1 (extract/inline method) to extract the `search` method achieving the program depicted in Fig. 2.

```

class BasicEntity {...} class Application {...
  method updateApplication(T1 num, T2 value; T2 reply ; ∅)
  { ... BasicEntity obj; ...
    { obj := data[i];
      reply := "Failed Updating"} < data[i] == null >
      {data[i].update(value); reply:= "Successful Updating"}}}

```

Fig. 4. Applying laws 3 ($;- \Leftarrow$ distrib), 7 (revised order independent assignment), 11 (assignment permutation) and 10 (revised assignment- \Leftarrow 2) in the example of Fig. 3.

5 Conclusions

Programming laws for imperative and concurrent languages are well established and have been proven useful in the design of applications of program transformation like compilers [24] and hardware/software partitioning [25]. The major contribution of this work is to provide a set of laws for object-oriented languages based on a reference semantics. We have considered laws already proposed for copy semantics, that are not valid for reference semantics, and for each of these laws, we have proposed a revised version for reference semantics. Furthermore, this work introduces new laws valid only for reference semantics. We are not aware of any other result in this direction.

A common criticism of the algebraic style is that merely postulating algebraic laws can give rise to complex and unexpected interactions between programming construction. This can be avoided by the verification of the laws in a mathematical model. Our laws have been proved sound with respect to rCOS semantics, as illustrated in the appendix.

Although the case study presented here is simple, it illustrates the benefits of using algebraic laws to improve code structure, in a sound way, in the presence of aliasing. To develop more elaborated case studies is an important future work. These case studies will be particularly useful to validate and possibly extend the proposed set of laws.

We have not presented laws to support data refinement. In a context of reference semantics, this is a challenging work. Although data refinement can be proved directly in the semantics, this tends to be a laborious task. We intend to investigate laws for data refinement in the style of Morgan's work [5], based on approaches to *confinement* [26].

A complementary work is the development of tools. An initial work in this direction has already been performed for laws of ROOL [27], using the rewriting system CafeOBJ [28]. We intend to extend this work in the context of reference semantics.

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A Proof of Law 11 (*assignment permutation*)

The proofs of this law use the following auxiliary results of designs and predicates, extracted from [7].

Law 15 (*predicate 1*) `true;false = false = false;true`

Law 16 (*;-predicate*)

$$P(v'); Q(v) \stackrel{def}{=} \exists v_0 \bullet P(v_0) \wedge Q(v_0), \text{ provided } \text{out}\alpha P = \text{in}\alpha' Q = \{v'\}$$

$\text{out}\alpha P$ is the output variables v' of P and $\text{in}\alpha Q$ is the input variables of Q .

The normal combinators of the programming language have exactly the same meaning as operators on the single predicates as they have on the double predicates of the refinement calculus.

Theorem 1. *Let P_1, P_2, Q_1 and Q_2 be predicates*

$$\begin{aligned} (P_1 \vdash Q_1) \triangleleft b \triangleright (P_2 \vdash Q_2) &= (P_1 \triangleleft b \triangleright P_2) \vdash (Q_1 \triangleleft b \triangleright Q_2) \\ (P_1 \vdash Q_1); (P_2 \vdash Q_2) &= (\neg(\neg P_1; \text{true}) \wedge \neg(Q_1; \neg P_2)) \vdash (Q_1; Q_2) \end{aligned}$$

An immediate consequence of this theorem is given below.

Corollary 1.

$$(true \vdash Q_1); (true \vdash Q_2) = true \vdash (Q_1; Q_2)$$

Proof.

$$\begin{aligned} &LHS \\ &= \langle \text{Theorem 1} \rangle \\ &\quad (\neg(\neg true; true) \wedge \neg(Q_1; \neg true)) \vdash (Q_1; Q_2) \\ &= \langle \text{predicate calculus and Law 15(predicate 1)} \rangle \\ &\quad (true \wedge true) \vdash (Q_1; Q_2) \\ &= \langle \text{boolean algebra} \rangle \\ &RHS \end{aligned}$$

To perform the proof of Law 11 (*assignment permutation*) we have to consider all possible forms of command c_1 . Here we prove the case when c_1 is a method call, as this situation happens in the case study.

Proof.

$$\begin{aligned} &\llbracket e.m(v, \emptyset, \emptyset); le := e \rrbracket \\ &= \langle \text{from UTP semantics} \rangle \\ &\quad \llbracket e.m(v, \emptyset, \emptyset) \rrbracket; \llbracket le := e \rrbracket \\ &= \langle \text{semantics of method call and assignment} \rangle \\ &\quad (true \vdash \exists C \in cname \bullet type(e) = C \wedge \llbracket var T x = v \rrbracket; \llbracket var C self = e \rrbracket; \\ &\quad \llbracket Execute(C.m) \rrbracket; \llbracket end self, x \rrbracket); (true \vdash \forall le \bullet \exists \bar{le} \bullet \bar{le}' = \langle value(e) \rangle.tail(\bar{le})) \\ &= \langle \text{semantics of variable declaration and undeclaration; semantics of method call;} \\ &\quad \text{Corollary 1; Law 16 (; -predicate) and predicate calculus} \rangle \\ &\quad (true \vdash \exists C \in cname \bullet type(e) = C \wedge \\ &\quad \exists v : T \bullet (\forall x, self \bullet \exists \bar{x}, \bar{self} \bullet \exists \bar{x}_0, \bar{self}_0 \bullet \bar{x}_0 = \langle value(v) \rangle.tail(\bar{x}) \wedge \\ &\quad \bar{self}_0 = \langle value(e) \rangle.tail(\bar{self}) \wedge \pi' = \{ \langle r, C, \sigma_0 \oplus \{a \mapsto v\} \rangle | r = ref(value(e)) \} \wedge \\ &\quad \bar{self}' = tail(\bar{self}_0) \wedge \bar{x}' = tail(\bar{x}_0)) \wedge (true \vdash \forall le \bullet \exists \bar{le} \bullet \bar{le}' = \langle value(e) \rangle.tail(\bar{le})) \\ &= \langle \text{predicate calculus, Corollary 1; Law 16 (; -predicate)} \rangle \\ &\quad true \vdash (\exists C \in cname \bullet type(e) = C \wedge \\ &\quad \exists v : T \bullet (\forall x, self \bullet \exists \bar{x}, \bar{self} \bullet \exists \bar{x}_0, \bar{self}_0 \bullet \bar{x}_0 = \langle value(v) \rangle.tail(\bar{x}) \wedge \\ &\quad \bar{self}_0 = \langle value(e) \rangle.tail(\bar{self}) \wedge \pi' = \{ \langle r, C, \sigma_0 \oplus \{a \mapsto v\} \rangle | r = ref(value(e)) \} \wedge \\ &\quad \bar{self}' = tail(\bar{self}_0) \wedge \bar{x}' = tail(\bar{x}_0)) \wedge \forall le \bullet \exists \bar{le} \bullet \bar{le}' = \langle value(e) \rangle.tail(\bar{le})) \\ &= \langle le \text{ is free in the previous predicate; predicate calculus} \rangle \\ &\quad true \vdash (\forall le \bullet \exists \bar{le} \bullet \bar{le}' = \langle value(e) \rangle.tail(\bar{le})) \wedge \\ &\quad (\exists C \in cname \bullet type(e) = C \wedge \exists v : T \bullet (\forall x, self \bullet \exists \bar{x}, \bar{self} \bullet \\ &\quad \pi' = \{ \langle r, C, \sigma_0 \oplus \{a \mapsto v\} \rangle | r = ref(value(e)) \} \wedge \bar{self}' = \bar{self} \wedge \bar{x}' = \bar{x})) \\ &= \langle \text{Law 16(; -predicate); Corollary 1; Theorem 1 and predicate calculus} \rangle \\ &\quad \llbracket le := e \rrbracket; \llbracket e.m(v, \emptyset, \emptyset) \rrbracket \\ &= \langle \text{from UTP semantics} \rangle \\ &\quad \llbracket le := e; e.m(v, \emptyset, \emptyset) \rrbracket \end{aligned}$$

□